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LIDAR DATA: INNOVATION PERSPECTIVES FOR CADASTRE

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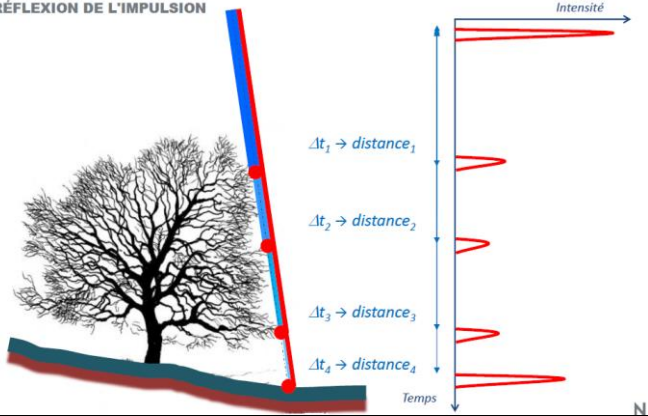
Institut national de l'information géographique et forestière

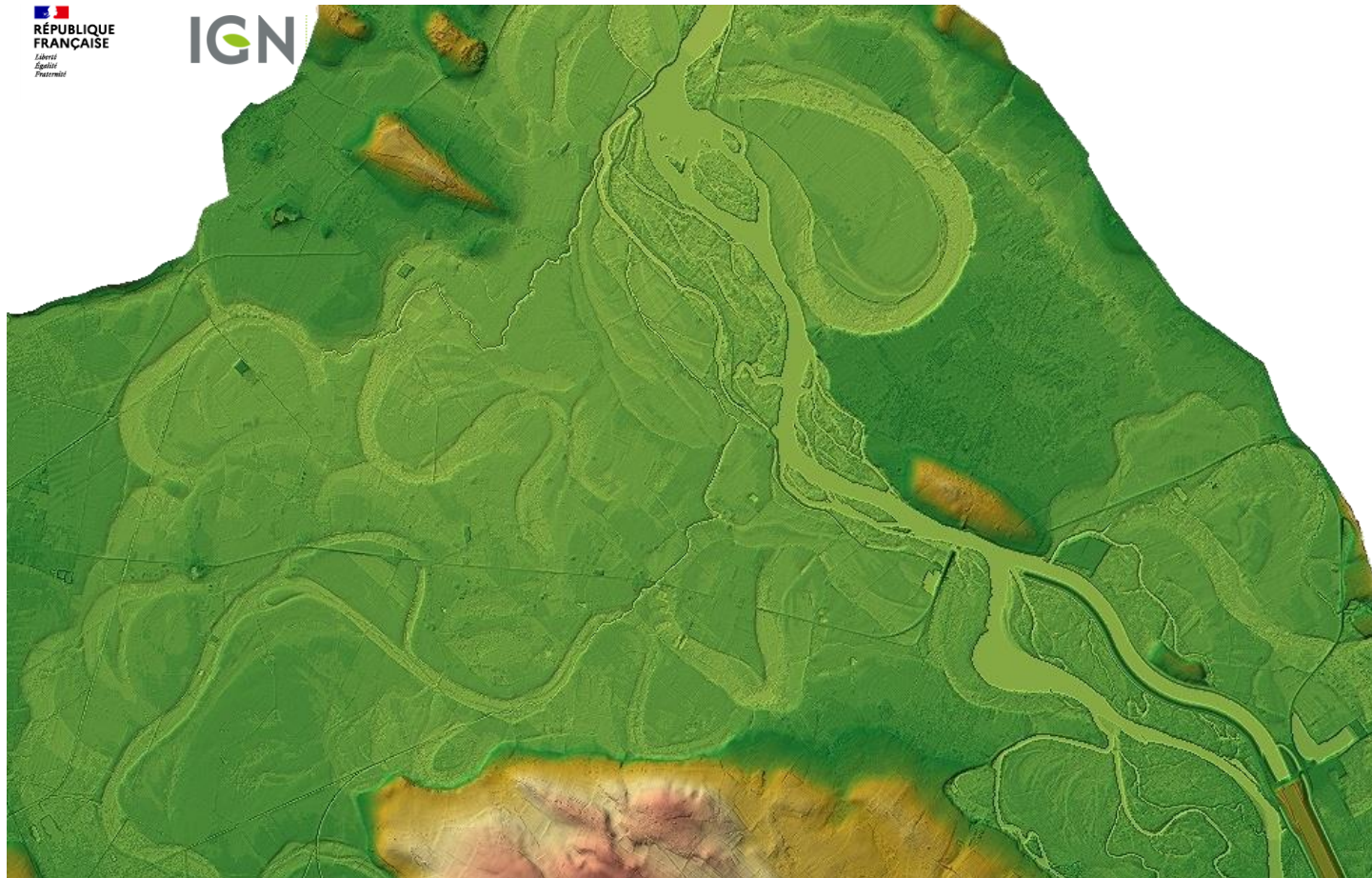
Lidar

light detection and ranging



RÉFLEXION DE L'IMPULSION

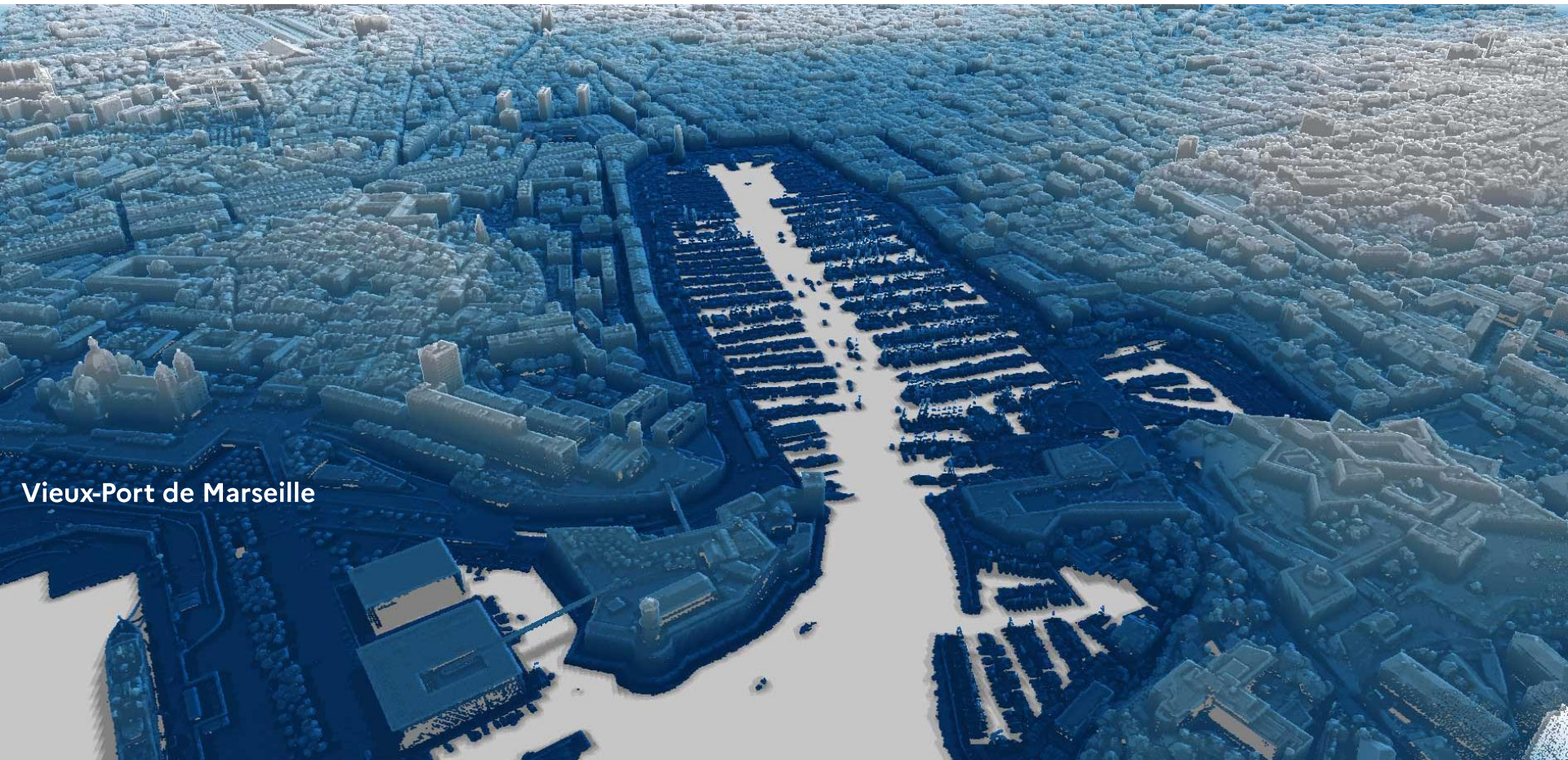




- IGN is setting up and coordinating a **national High Density Lidar (HD) programme** to address various public policies (agriculture, forestry, flood risk prevention in particular). IGN is involved in all phases :
 - Acquire airborne Lidar data with 10 pts/m² minimum
 - Process the Lidar point clouds to meet the various needs of public policies, and transform raw point clouds into classified ground/"above the ground" point clouds and DTMs
 - Host and disseminate the point clouds and processing results in open data,
 - Support users in the manipulation of point clouds and their by-products.
- Implementation over 5 years
- **Every product and derived product will be provided in open-data.**

<https://geoservices.ign.fr/lidarhd>






Vieux-Port de Marseille

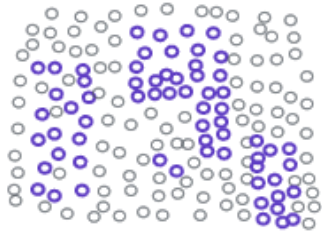
- Georeferencing
- **Data classification :**
 1. Topographic ground
 2. Others
 - Vegetation
 - Buildings
 - Bridges
 - Etc.
- From point cloud data to :
 - DTM
 - vector data → BIM

Huge data volume
AI solutions are experimented

Mix approach :  classification + existing geodatabases + AI prediction

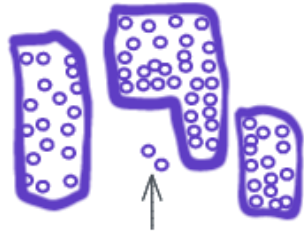
General overview

Terrasolid classification



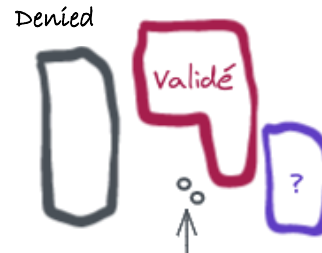
- Potential building points
- Other points

Grouping by connected component



Building point too isolated to belong to a group

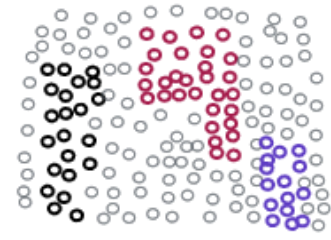
Final decision based on AI + existing databases



Denied


3

Propagation

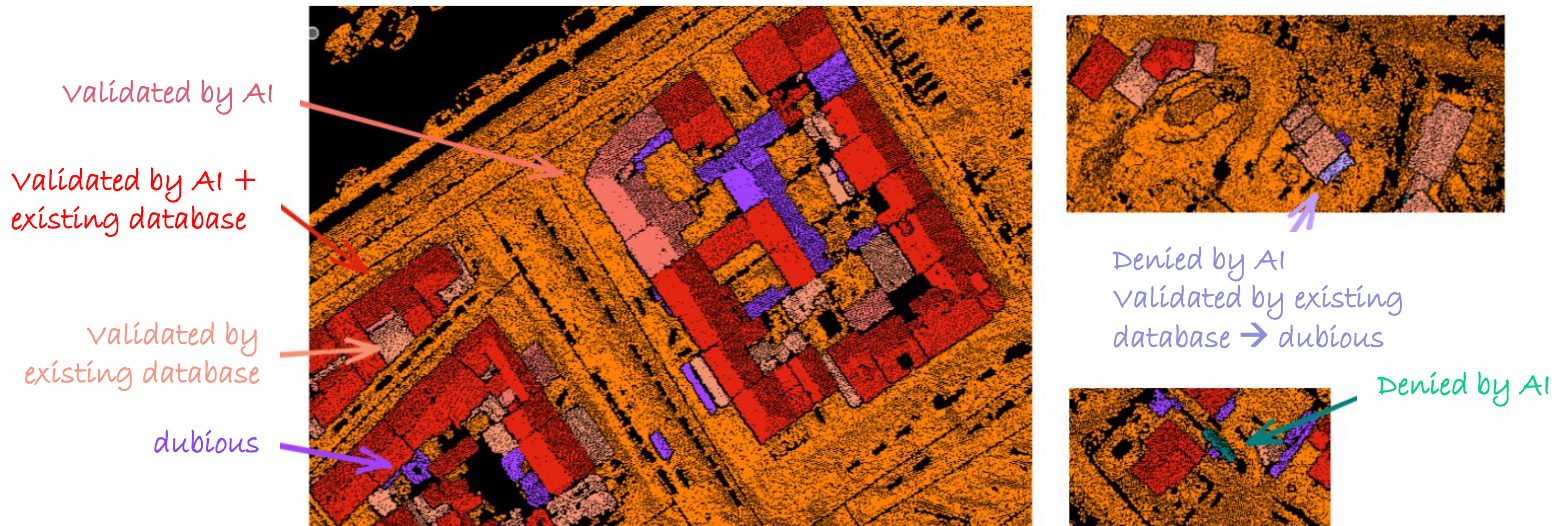


- Building point confirmed
- Building point denied
- Potential building points to check
- Other points

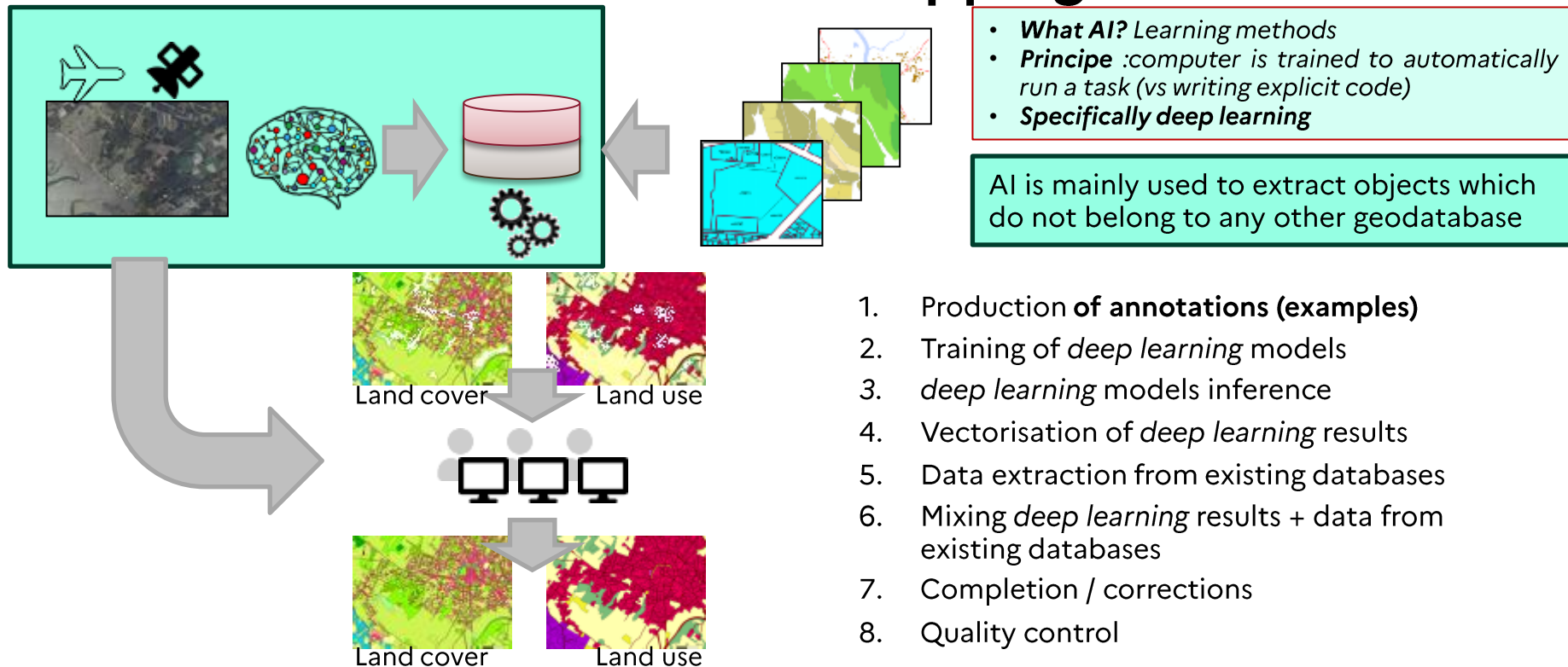
4

Mix approach :  classification + existing geodatabases + AI prediction

-
- improves the reliability of building detection
 - drastically reduces the need for manual inspection/edition



AI automation of land cover mapping



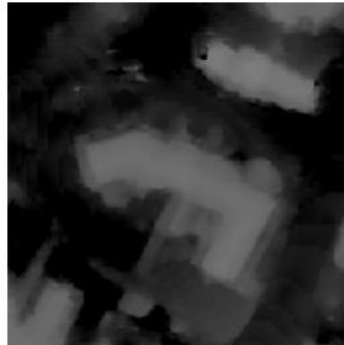
AI automation of building mapping

- RGB orthoimage
- False color orthoimage
- Height (DSM – DTM)



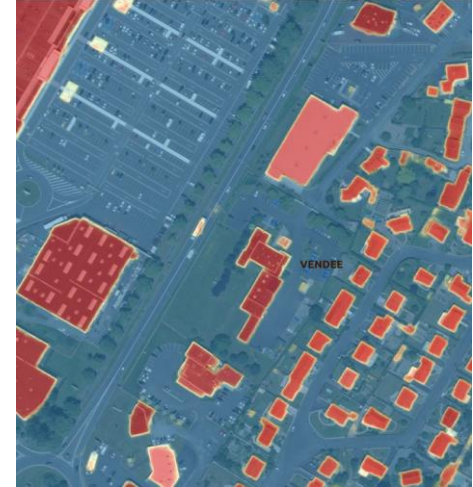
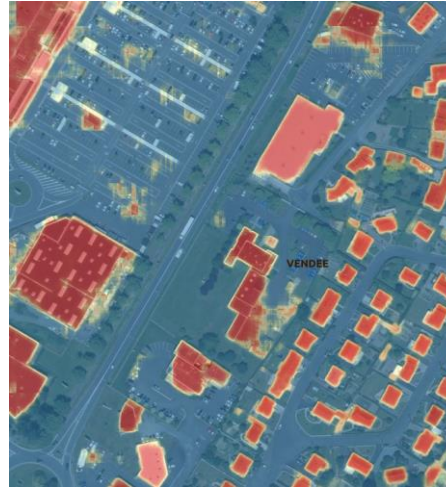
Infrared :

- Vegetation
- Non vegetation



Height :

- Building
- Road



Building detection without / with height information

Backbone : democratise AI

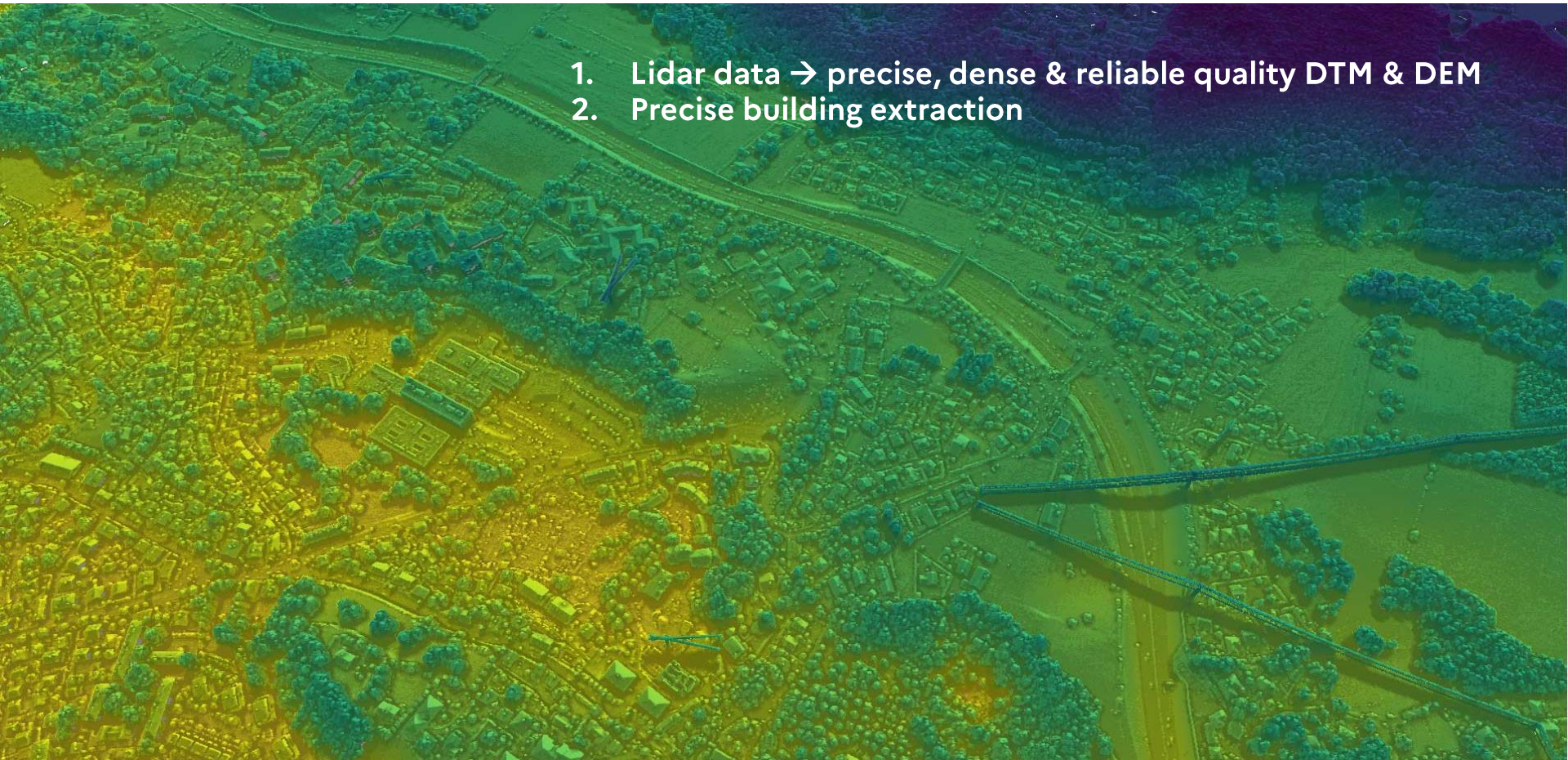
3 main objectives :

1. maintain the technical capacities to keep on working on the ongoing projects
2. Keep some extra resources to
1) stay up to date & 2)
consider new projects
3. Support / contribute to AI communities / take an active part to ecological transition

5 axes :

1. Rely on commons
2. Make AI accessible at all levels
3. Create and maintain good conditions to reach the goals
4. Debate + socially and ecologically regulate AI deployment
5. Support major scientific orientations

1. Lidar data → precise, dense & reliable quality DTM & DEM
2. Precise building extraction

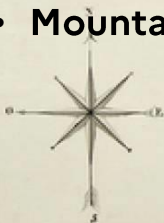




First use case : good contribution to precise georeferencing

Lidar for cadastre

1. French cadastre is heterogeneous, as far as geometric absolute accuracy is concerned.
2. From paper maps to vectorised plan **digitisation** caused various problems like :
 - Poor georeferencing accuracy
 - Lack of continuity between adjacent sheets
3. IGN is currently involved in a joint project with DGFIP meant to optimise representation of the French cadastral maps. IGN is specifically involved in **improving the georeferencing accuracy of cadastral sheets**.
4. **Main difficulties occur with**
 - Napoleon cadastral maps,
 - Mountain, forest or wooded countryside

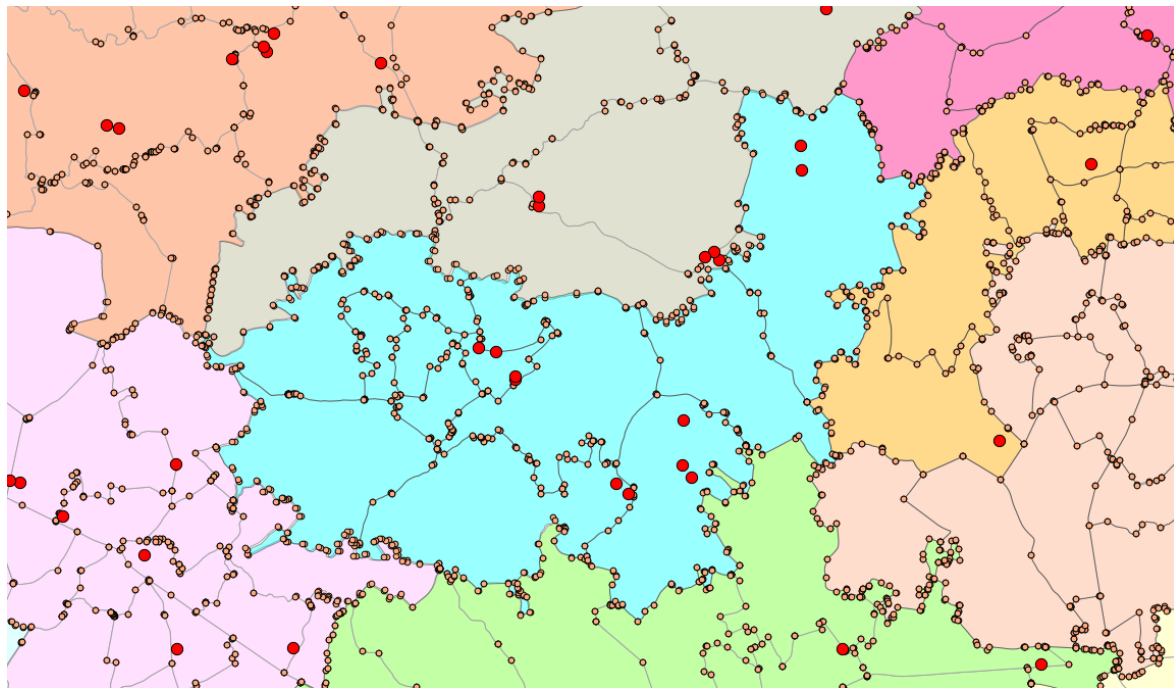


3 complementary ideas to get around the difficulties

1. Use a block adjustment method to georeference several sheets with few GCP
2. Rely on more ground control points (GCP)
3. Rely on information provided by Lidar data

3 complementary ideas to get around the difficulties

1. Use a block adjustment method to georeference several sheets with few GCP*



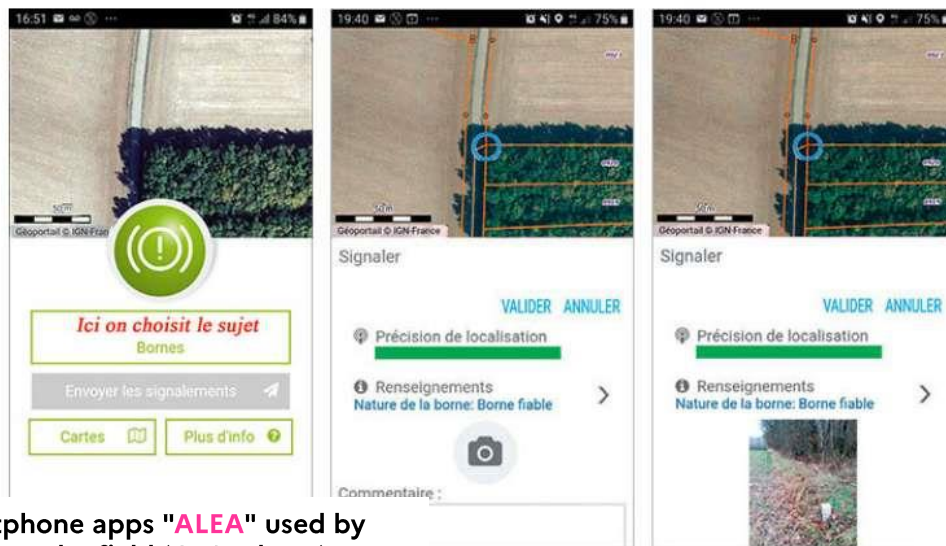
Mathematic transformation is usually computed for each sheet

Block adjustment method makes it possible to compute transformations for several sheets at once 1) with few GCP 2) constraining the continuity between adjacent sheets

- Ground control points (GCP) :
 - visible on the map
 - known in a cartographic reference system
- Tie points
 - Same detail seen on adjacent sheets

3 complementary ideas to get around the difficulties

2. Rely on more ground control points (GCP) : collaborative campaign to collect information on old landmarks



1. smartphone apps "ALEA" used by anyone on the field (GPS+photo) to report existing landmark

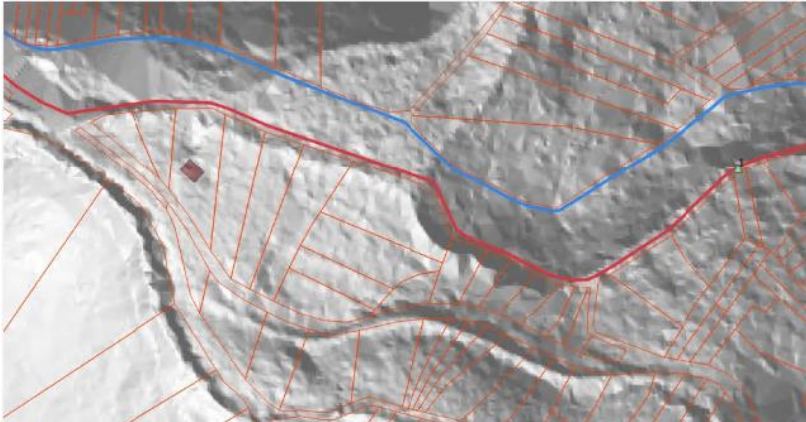
Signalez une borne en trois clics sur l'application



2. Precise GPS RTK measurement

3 complementary ideas to get around the difficulties

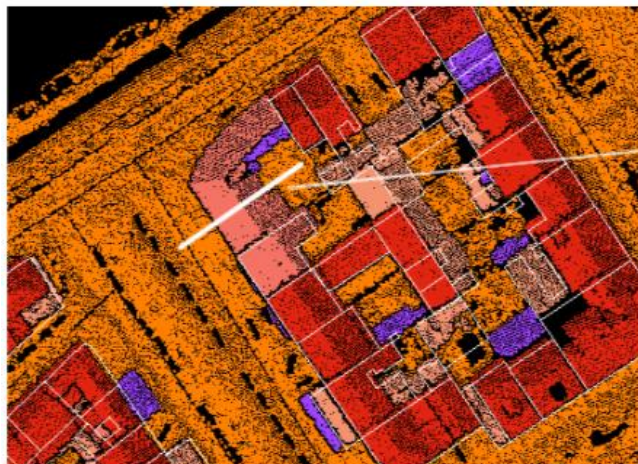
3. Rely on information provided by Lidar data



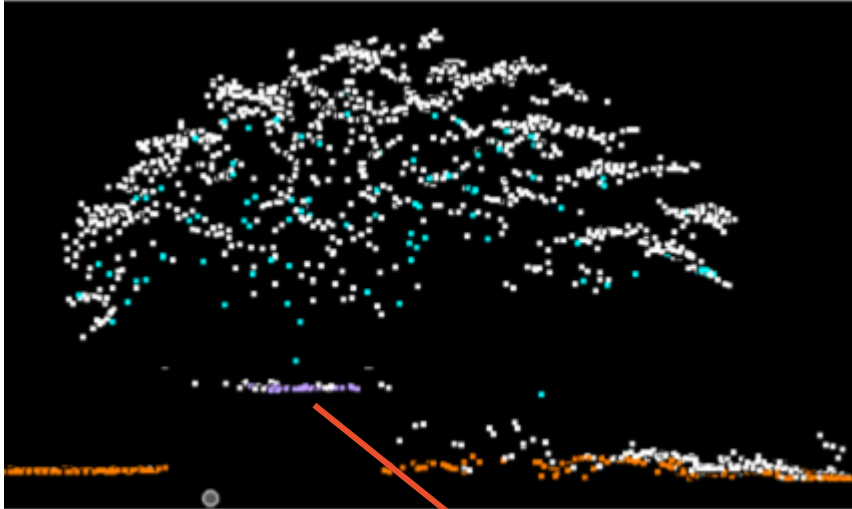
Lidar data shows structuring items **even under vegetation cover** like :

- road, path ...
- stream, ditch ...

Precise building extraction



Precise building extraction



3D points under the trees



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THANK YOU

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