

ISO 19157-3

Quality Measure Register

Project leaders

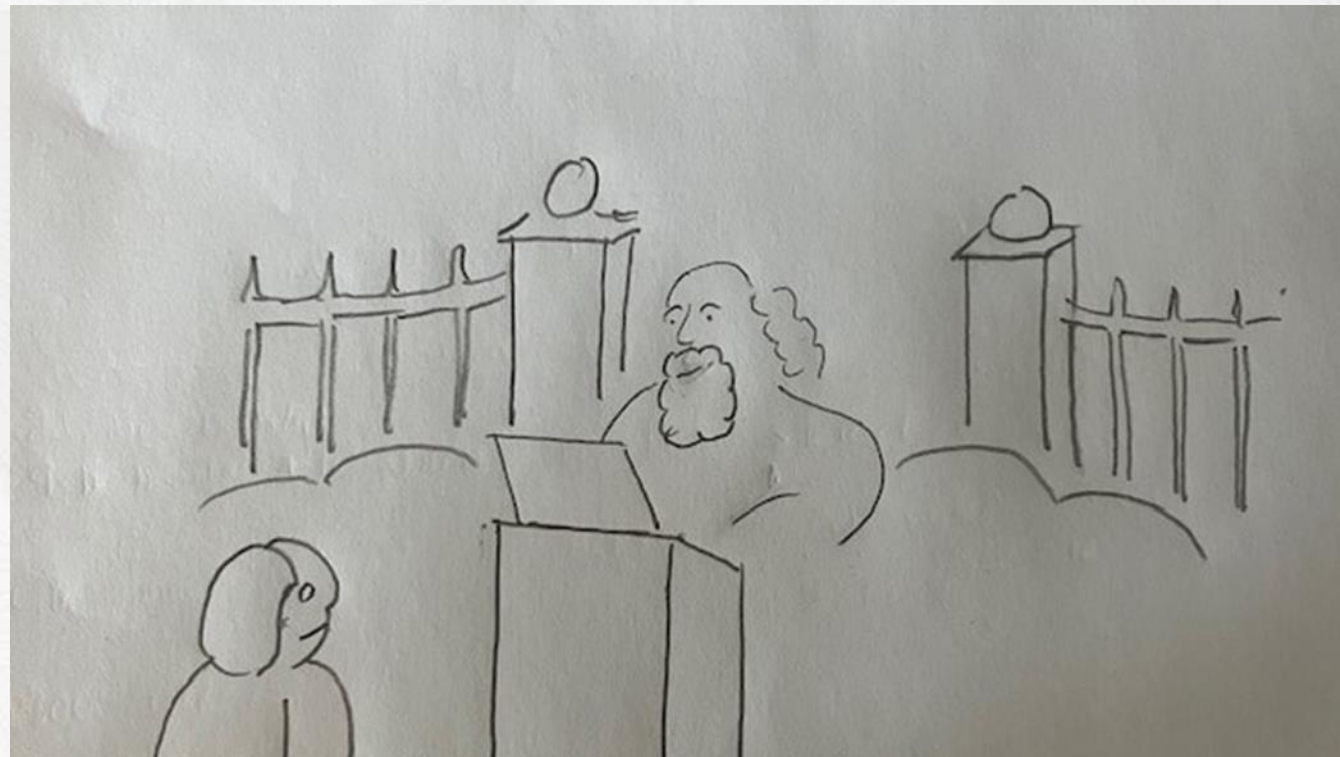
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and

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Today's talk

- Why we saw a need for a Data Quality Measure register
- How it works in practice
- How it will be managed
- What is going on



'Sorry'

You missed the last update for a Quality measure, next review will be planned to 2027

From the past...

Data quality measures in earlier version of the quality standard were in a normative annex typeset as tables in a PDF:

- ISO 19138:2006
- ISO 19157:2013

Currently ISO 19157-3 (expected publication in 2025)

...to the future

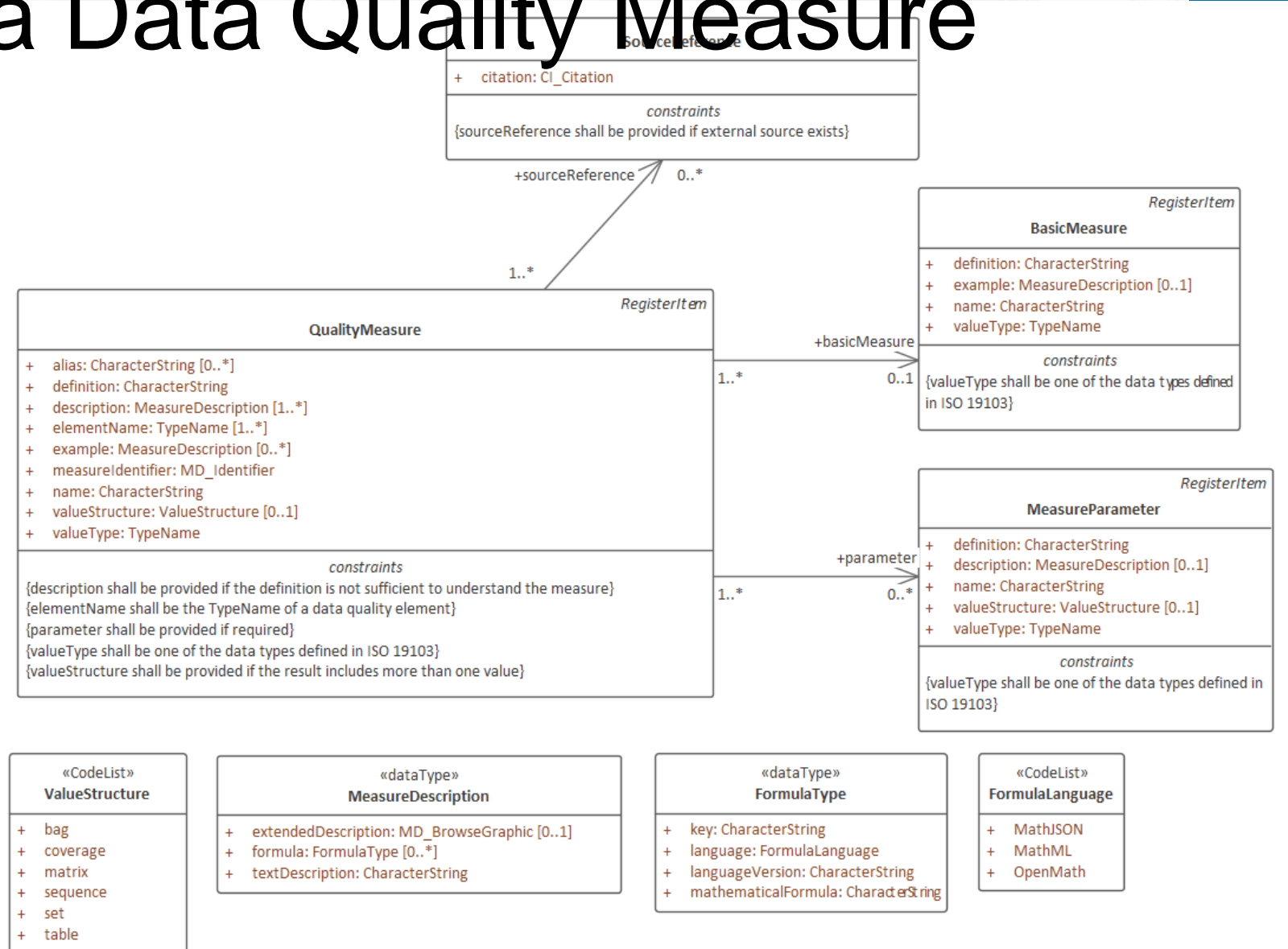
- Readable for a human
- Readable and actionable for a machine
- New measures can be added easily, as per procedures defined in ISO 19157-3
- Informative register
- The register Owner is ISO TC 211
- The registration authority is OGC, confirmed in 2022
- A control body with experts defined in 19157-3

Structure of a Data Quality Measure

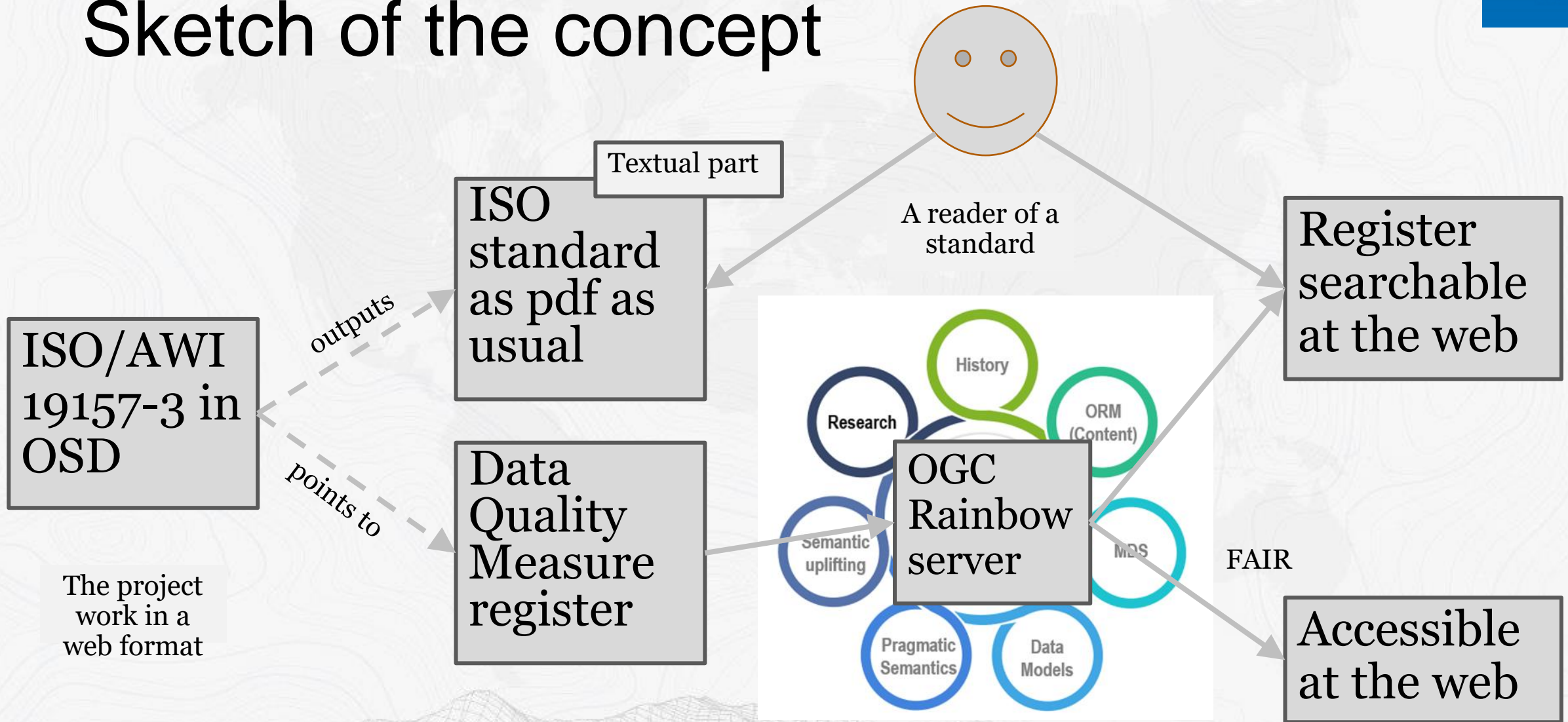
From ISO 19157-1:2023

Beside this there is register content from 19135:

- Status of an item
 - Versioning of items
 - URI
- ... and other metadata



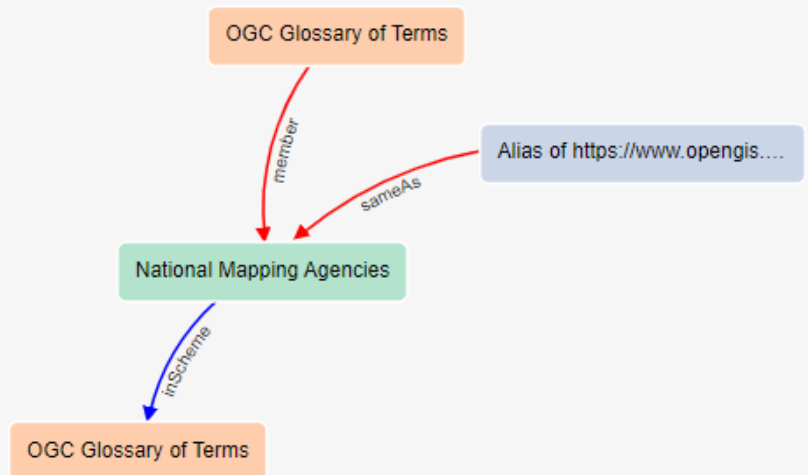
Sketch of the concept



The project work in a web format

OGC RAINBOW

- A Web accessible source of information about things
- The “core” OGC RAINBOW can be accessed at <https://www.opengis.net/def> and holds definitions for terms defined by OGC
example: National Mapping Agencies (preferred label)
URI: <http://www.opengis.net/def/glossary/term/NationalMappingAgencies>



Definition

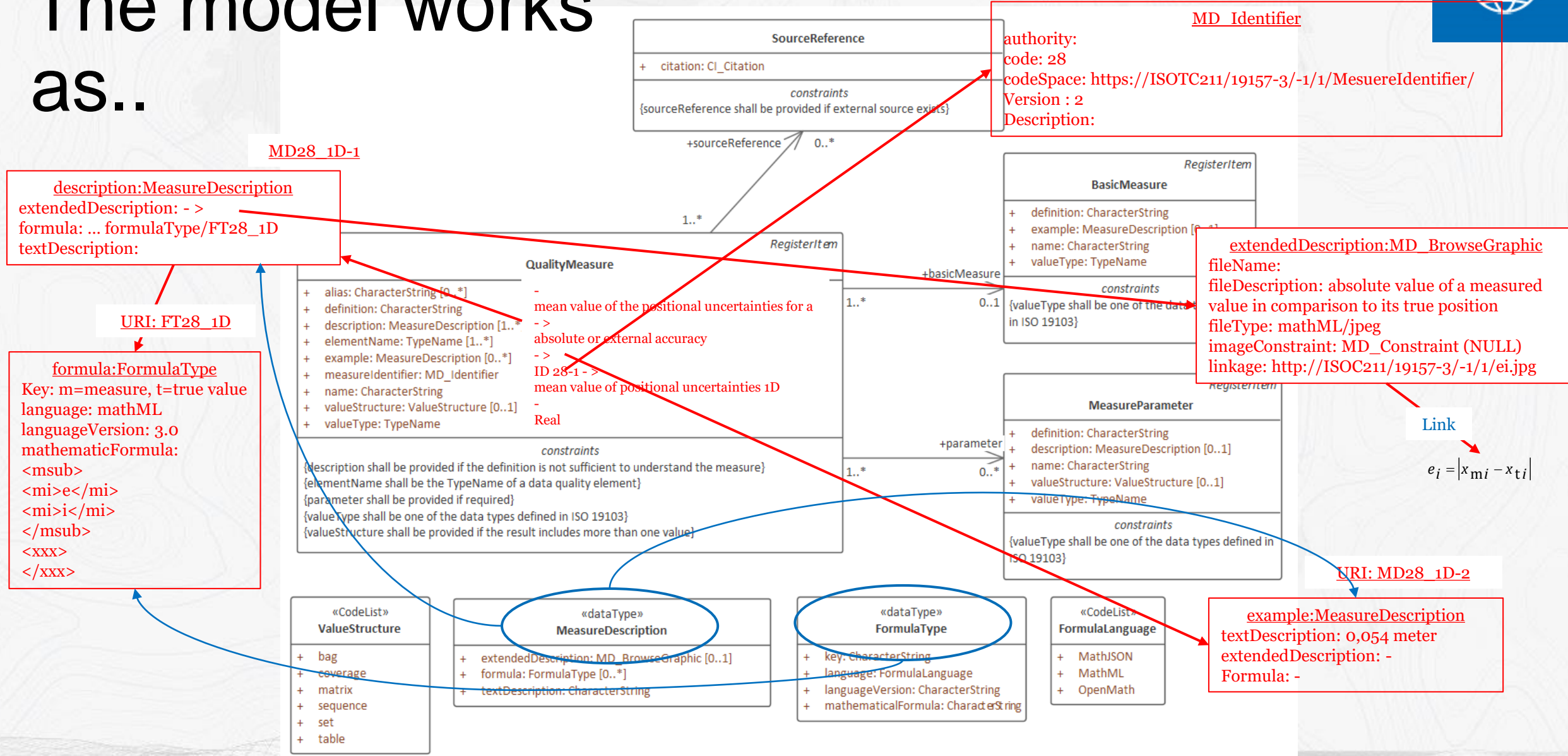
National government agencies, such as the UK's Ordnance Survey, France's Institut Geographique National (IGN) and the US's US Geological Survey and Federal Geographic Data Committee, that are chartered to provide national mapping products and services

Data quality measures register

- From ISO 19157:2013:
 - Clause 8 (Defining DQ measures) stays in ISO 19157-1
 - Annex D goes to ISO 19157-3 online register.
- New in ISO 19157-3:
 - Roles, management & procedures for DQ Measures registration

Line	Component	Description
1	Name	mean value of positional uncertainties (1D, 2D and 3D)
2	Alias	-
3	Element name	absolute or external accuracy
4	Basic measure	not applicable
5	Definition	mean value of the positional uncertainties for a set of positions where the positional uncertainties are defined as the distance between a measured position and what is accepted as the corresponding true position
6	Description	<p>For a number of points (N), the measured positions are given as x_{mi}, y_{mi} and z_{mi} coordinates depending on the dimension in which the position of the point is measured. A corresponding set of coordinates, x_{ti}, y_{ti} and z_{ti}, are considered to represent the true positions. The positional uncertainties are calculated as:</p> <p>1D: $e_i = x_{mi} - x_{ti}$</p> <p>2D: $e_i = \sqrt{(x_{mi} - x_{ti})^2 + (y_{mi} - y_{ti})^2}$</p> <p>3D: $e_i = \sqrt{(x_{mi} - x_{ti})^2 + (y_{mi} - y_{ti})^2 + (z_{mi} - z_{ti})^2}$</p> <p>The mean positional uncertainties of the horizontal absolute or external positions are then calculated as</p> $\bar{e} = \frac{1}{N} \sum_{i=1}^N e_i$ <p>A criterion for the establishing of correspondence should also be stated (e.g. allowing for correspondence to the closest position, correspondence on vertices or along lines). The criterion/criteria for finding the corresponding points shall be reported with the data quality evaluation result.</p>
7	Parameter	-
8	Value type	Real
9	Value structure	-
10	Source reference	-
11	Example	0,054 meter
12	Identifier	28

The model works as..



MD_Identifier
 authority:
 code: 28
 codeSpace: https://ISOTC211/19157-3/-1/1/MesureIdentifier/
 Version : 2
 Description:

MD28_1D-1
 description: MeasureDescription
 extendedDescription: ->
 formula: ... formulaType/FT28_1D
 textDescription:

extendedDescription: MD_BrowseGraphic
 fileName:
 fileDescription: absolute value of a measured value in comparison to its true position
 fileType: mathML/jpeg
 imageConstraint: MD_Constraint (NULL)
 linkage: http://ISOC211/19157-3/-1/1/ei.jpg

URI: FT28_1D
 formula: FormulaType
 Key: m=measure, t=true value
 language: mathML
 languageVersion: 3.0
 mathematicFormula:
 <msub>
 <mi>e</mi>
 <mi>i</mi>
 </msub>
 <xxx>
 </xxx>

Link

$$e_i = |x_{mi} - x_{ti}|$$

URI: MD28_1D-2
 example: MeasureDescription
 textDescription: 0,054 meter
 extendedDescription: -
 Formula: -

DQM – An example of a formula on OGC RAINBOW

<p>Concept</p> <p>Preferred Label</p> <p>FT28_1</p> <p>URI</p> <p>https://standards.iso211.org/19157/-3/1/dqc/content/formulaType/FT28_1</p> <p>Within Vocab</p> <p>ISO19157-3 Quality Measures Formulas</p>	<p> ■ ConceptScheme ■ Concept </p> <p>Definition</p> <p>http://www.opengis.net/def/metamodel/isodqm/formulaKey</p> <p>http://www.opengis.net/def/metamodel/isodqm/formulaLanguage</p> <p>http://www.opengis.net/def/metamodel/isodqm/formulaLanguageVersion</p> <p>1.0</p>	<p> $e_i = x_{mi} - x_{ti}$ </p> <p>For a number of points (N), the measured positions are given as x_{mi}, y_{mi} and z_{mi} coordinates depending on the dimension in which the position of the point is measured. A corresponding set of coordinates, x_{ti}, y_{ti} and z_{ti}, are considered to represent the true positions. Formula for 1D positional uncertainty.</p> <p>MathML</p>
		<pre> graph TD MD28-1[MD28-1] -- formula --> FT28_1[FT28_1] FT28_1 -- nScheme --> ISO19157-3[ISO19157-3 Quality Measures F...] </pre>

Example in turtle form

Formula.ttl

```

<https://standards.iso/2015/10/15/iso/10157/-3/1/dqc/content/formulaType/FT28_1> a skos:Concept ;
    dqm:formulaKey "For a number of points (N), the measured positions are given as xmi , ymi and
zmi coordinates depending on the dimension in which the position of the point is measured. A
corresponding set of coordinates, xti , yti and zti , are considered to represent the true positions.
Formula for 1D positional uncertainty." ;
    dqm:formulaLanguage "MathML" ;
    dqm:formulaLanguageVersion "1.0" ;
    skos:definition "<math xmlns=\\"http://www.w3.org/1998/Math/MathML\">
    <msub><mi>e</mi><mi>i</mi></msub><mo>=</mo>
    <mfenced close=\\"|\"open=\\"|\"><mrow><msub><mi>x</mi>
    <mrow><mi>m</mi><mi>i</mi></mrow></msub><mo>-</mo>
    <msub><mi>x</mi><mrow><mi>t</mi><mi>i</mi></mrow>
    </msub></mrow></mfenced></math>" ;
    skos:inScheme <https://standards.iso/2015/10/15/iso/10157/-3/1/dqc/content/formulaType> ;
    skos:prefLabel "FT28_1" .

```

Example in JSON-LD form

```
[
  {
    "@id": "https://standards.iso/211.org/19157/-3/1/dqc/content/formulaType/FT28_1",
    "@type": [
      "http://www.w3.org/2004/02/skos/core#Concept"
    ],
    "http://www.opengis.net/def/metamodel/isodqm/formulaKey": [
      {
        "@value": "For a number of points (N), the measured positions are given as xmi , ymi and zmi coordinates depending on the dimension in which the position of the point is measured. A corresponding set of coordinates, xti , yti and zti , are considered to represent the true positions. Formula for 1D positional uncertainty."
      }
    ],
    "http://www.opengis.net/def/metamodel/isodqm/formulaLanguage": [
      {
        "@value": "MathML"
      }
    ],
    "http://www.opengis.net/def/metamodel/isodqm/formulaLanguageVersion": [
      {
        "@value": "1.0"
      }
    ],
    "http://www.w3.org/2004/02/skos/core#definition": [
      {
        "@language": "en",
        "@value": "<math xmlns='\"http://www.w3.org/1998/Math/MathML\"'><msub><mi>e</mi><mi>i</mi></msub><mo>=</mo><mfenced close='\"|\"' open='\"|\"'><mrow><msub><mi>x</mi></msub><mi>m</mi><mi>i</mi></mrow></msub><mo>-</mo><msub><mi>x</mi></msub><mi>t</mi><mi>i</mi></msub></mrow></mfenced></math>"
      }
    ],
    "http://www.w3.org/2004/02/skos/core#prefLabel": [
      {
        "@language": "en",
        "@value": "FT28_1"
      }
    ]
  }
]
```

ISO 19157-3: Updates

- ISO 19157-3 strongly depends on ISO 19135 currently under revision
- ISO/CD 19157-3 timeline slightly delayed
- No significant impact expected on the DIS timing – timing of ISO 19135 and its impact on ISO 19157-3 closely monitored.

Whats up now

- The review of 19135 is late
- But we still working for CD this year and DIS in april 2024
- OGC acts as Registration Authority and will set up the register
- A Control Body will be set up
- Processes will be set up to manage new measures, included in the standard

Thank you!

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